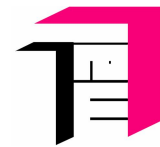


---

# Quirks and Challenges in the Design and Verification of Reliable, Efficient, High-Load Real-Time Software Systems

Ulrich Margull      1 mal 1 Software GmbH



Michael Niemetz    Continental Automotive GmbH,  
Gerhard Wirrer    Regensburg



# Motivation

---



chromed molding, color of the paintwork, engine power, width of tires, crash protection, exhaust valves, leather coated seats, Xenon headlights, maximum velocity, sports suspension

CPU-Frequency????

# Motivation

---

- ▶ An engine control system (ECS) has to perform many tasks with a wide spread of deadlines ranging from less than 1  $\mu\text{s}$  to several seconds
- ▶ In its core functionality, many of the deadlines ...
  - ▶ ... are quite "hard", since they are related to the rotating engine, e.g. points in time for injection and ignition
  - ▶ ... and at the same time very fast, e.g. in the  $\mu\text{s}$  time range for injector control
- ▶ High reliability
- ▶ High safety requirements
- ▶ Due to the market requirements and high volumes, a highly efficient resource consumption and design-to-cost principles are mandatory for system development

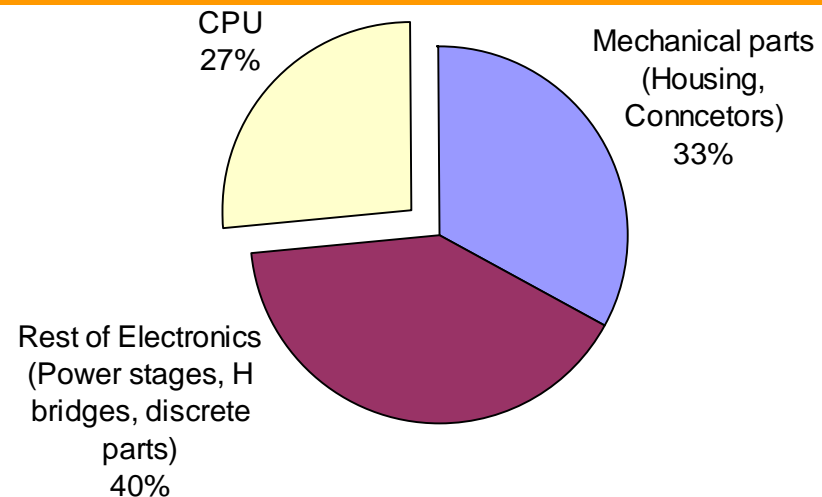
# Motivation: Why does Anybody want a 95% CPU Load?

- ▶ CPU is most expensive hardware element in the EBOM (~40%)
  - ▶ BOM = bill of materials
  - ▶ EBOM = BOM of electronic parts + circuit board
- ▶ High volumes (up to the millions per year)
- ▶ Due to high volumes, software development costs are much smaller than BOM costs

=> savings in BOM will be realized almost independently of the software development costs !

## ▶ Example:

- ▶ 500k Pieces / year
- ▶ 10 € EBOM

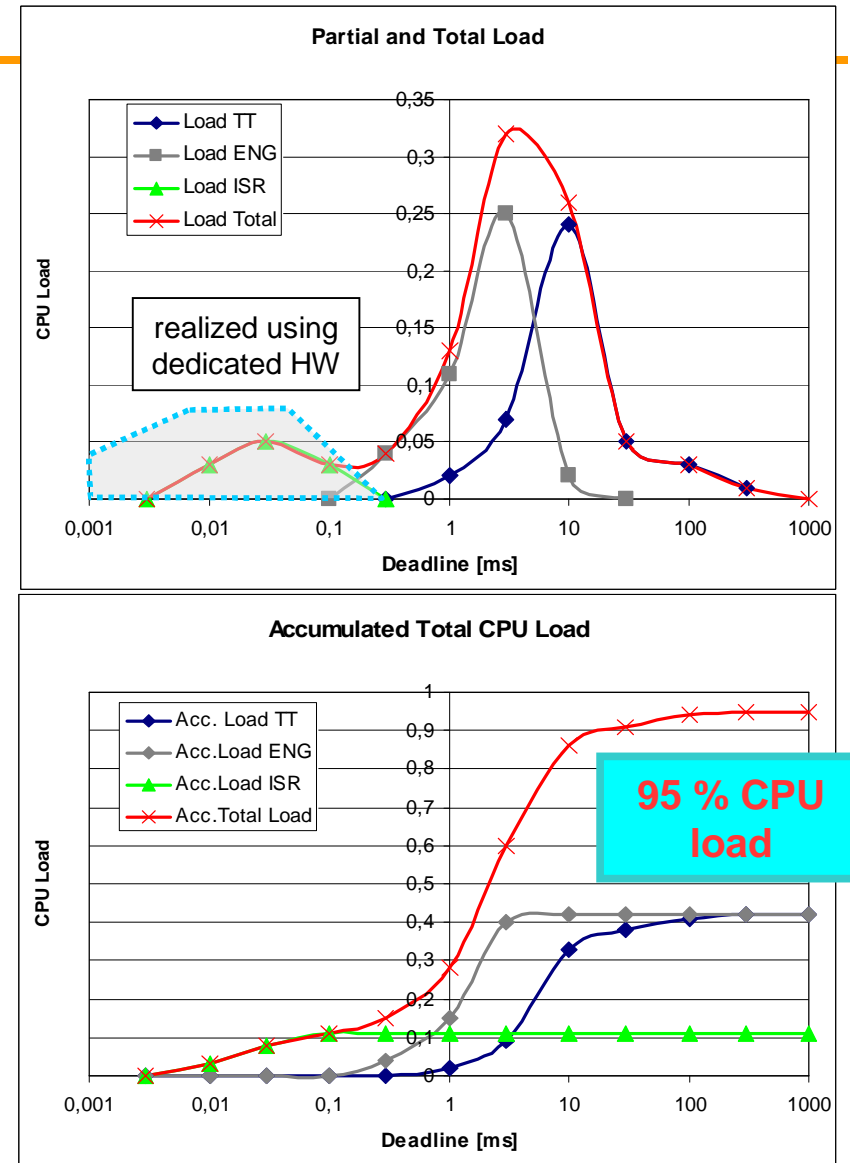


Overall Project Costs



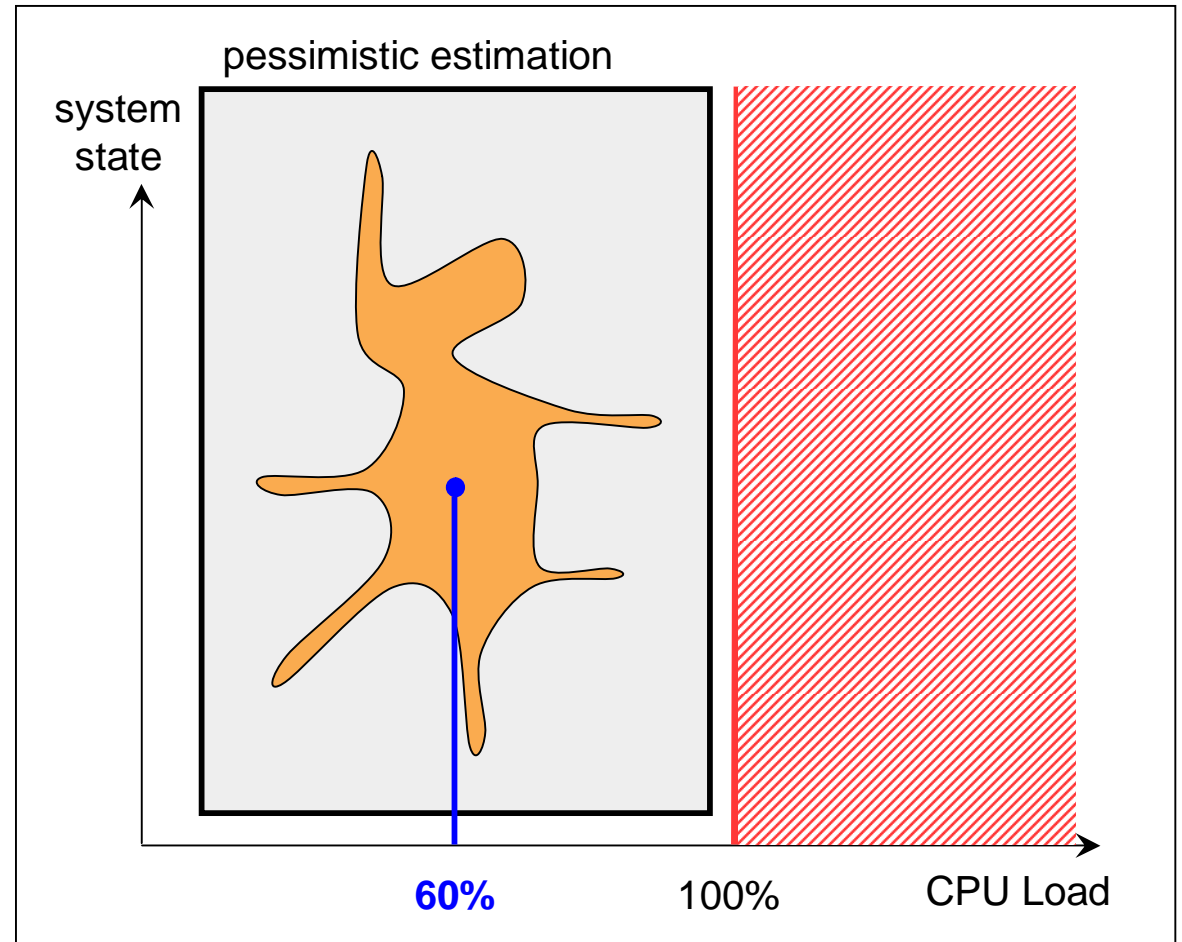
# Characterization of System Dynamics

- ▶ An ECS has to perform many tasks with a wide spread of deadlines ranging from less than 1us to several seconds
- ▶ Software on the CPU can cover a range from some microseconds up to long-time calculations
- ▶ Hierarchical composition according to deadlines
  - ▶ each time range should be robust against some overload conditions
  - ▶ try hard to make each deadline a “soft deadline” (degradation of service instead of failure)



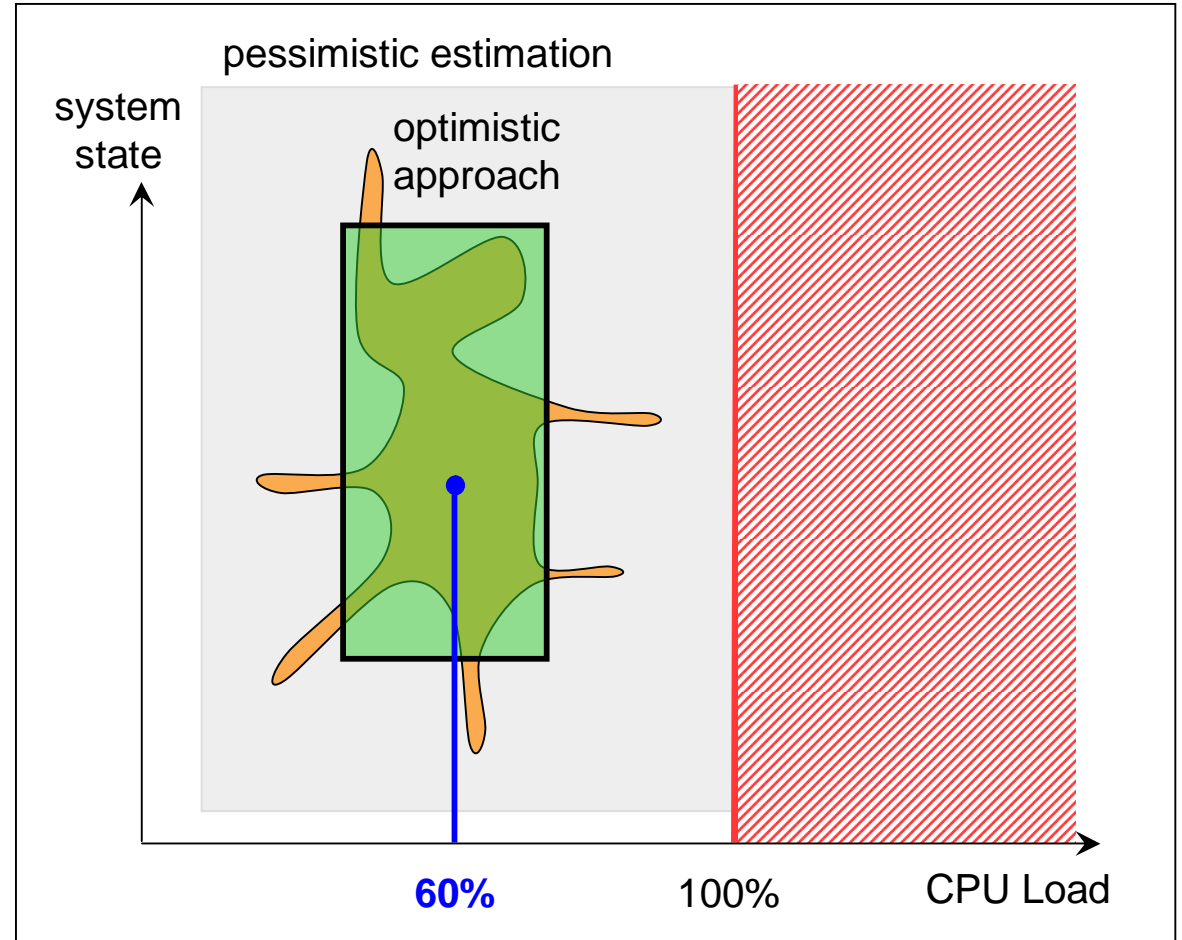
# Development Challenges

- ▶ Classic analysis uses pessimistic approaches (e.g. WCET)
- ▶ Even with very exact estimates only a medium average CPU load (e.g. 60%) can be achieved



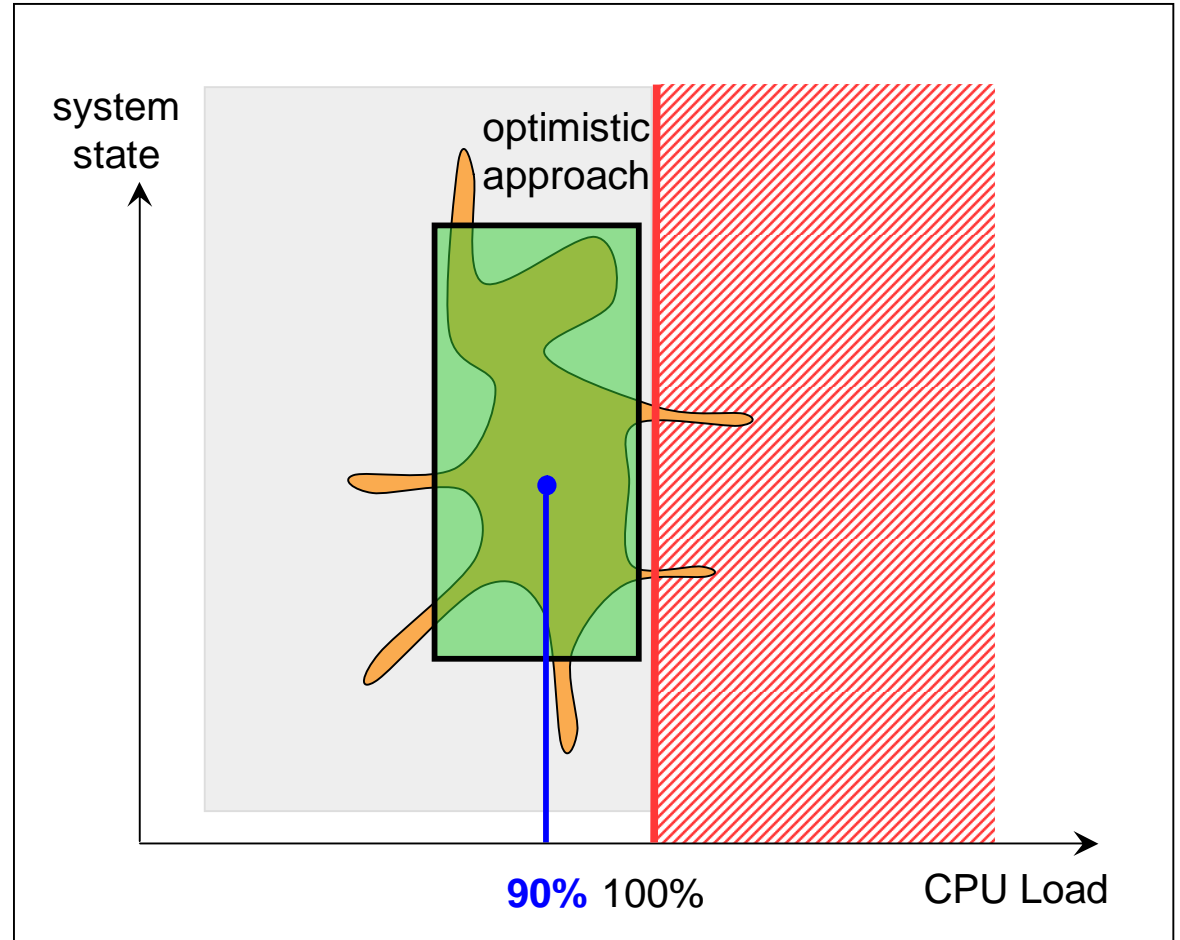
# Development Challenges

- ▶ System must be robust way, i.e. temporary overload
- ▶ Using an optimistic approach, most of the system state is covered, but not all
- ▶ This allows a much more efficient system design



# Development Challenges

- ▶ Using an optimistic approach, most of the system state is covered, but not all
- ▶ This allows a much more efficient system design
- ▶ and higher average CPU loads
- ▶ Two-fold advantage:
  - ▶ ... smaller CPU (for the functionality)
  - ▶ ... or more functionality (with the same CPU)





# Example:

## Validation of the Timing Behavior of an ECU using Simulation

---

- ▶ Build a model of the system (choose the necessary abstraction level)
  - ▶ Based on OSEK OS
  - ▶ Tasks replaced stubs using the measured runtimes (**average** value)
- ▶ Analyze the behavior using **simulation techniques** Optimistic approach
  - ▶ Use suitable metrics to quantify the simulation results  
F. König, et.al., *Application Specific Performance Indicators for Quantitative Evaluation of the Timing Behavior for Embedded Real-Time Systems*, Date 2009
- ▶ Benefits
  - ▶ High flexibility: existing software can be modeled with the necessary complexity (e.g. mix of preemptive / cooperative behavior, mix of different scheduling approaches, correlation between software behavior, sporadic behavior of calculations)
  - ▶ Increased reliability due to stress tests
  - ▶ Better understanding of internal dynamics: simulation gives a "white-box" view of the system

R. Münzenberger, et.al., *Entwurf echtzeitfähiger Steuergerätesoftware in FlexRay-Netzwerken*, KFZ Entwicklerforum 2007

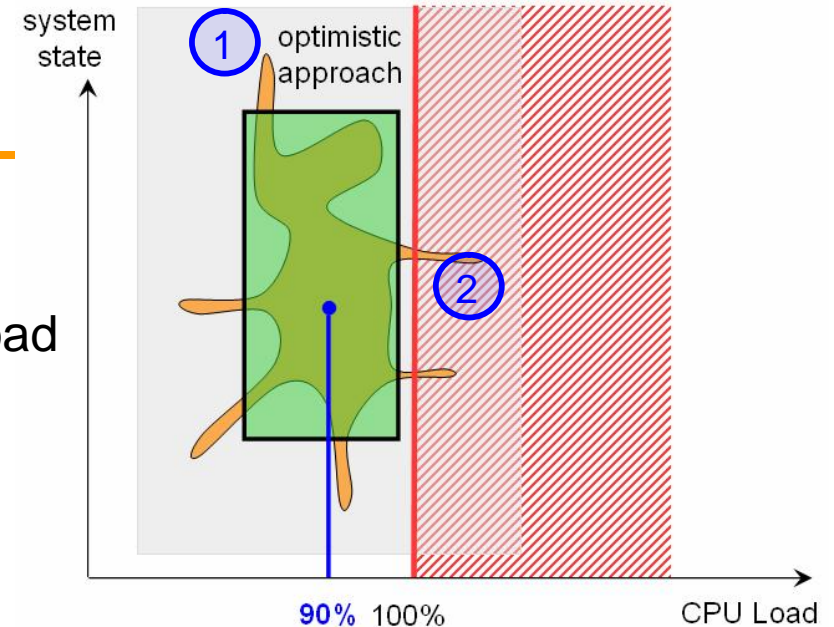
---

# Development Challenges

---

## Important questions

- ▶ How "robust" is the system against temporary overload conditions ?
- ▶ How large are the areas that are not covered by the "optimistic approach" ? (1)
- ▶ What is the the impact of those areas ? (2)
- ▶ How can the areas be minimized or completely removed ?
- ▶ How can the "optimistic approach" be improved ?
- ▶ What are good design principles when using the optimistic approach ?
- ▶ What are good validation principles when using the optimistic approach ?



# Summary & Required New Concepts

---

- ▶ Highly efficient hard real-time systems are possible in the Automotive domain with
  - ▶ ... CPU loads up to 95%
  - ▶ ... high reliability as well as strong safety requirements

However, research is needed to support the development of  
reliable **and** cost-efficient real time systems.

## Involved fields:

- ▶ Design principles
  - ▶ Classification of systems (cyclic, acyclic, ...)
  - ▶ Algorithms (functional algorithms, scheduling strategies)
  - ▶ Hierarchic deadline realization
  - ▶ Hardware / software co-design
- ▶ Verification/Validation concepts



Thank you for your attention